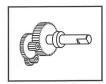
# Features of a first quality motor

Characteristics	Benefits
Skewed lamination stack Unique brush rigging Low inductance Thick magnets All metal housing	<ul> <li>→ low cogging, high speed control range</li> <li>→ low noise, long brush life</li> <li>→ low RFI, long brush life</li> <li>→ highly resistant to demag current</li> <li>→ good thermal dissipation, RFI shielding</li> </ul>

#### **Gearboxes**



To adjust load torque and load speed requirements to the motor capabilities. A full line of gears is available.

#### Low cost integral gearboxes

Spur gear designs with uncentered output shaft

Ty	ре	Cont.	torque	Avail	able on
MGM	8000	0.7	Nm	M	8000
MGM	9000	1.2	Nm	M	9000
MGM	14000	6	Nm	M	14000

Please refer to the corresponding motor page for detailed informations.

### High performance gearboxes

are selected for compact size, centered output shaft and long life requirements

## Spur gearboxes

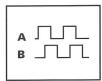
Туре	Cont. torque
K 38	0.6 Nm
K 40	1.2 Nm
RG 1/8	0.6 Nm
RG 1/9	1.2 Nm

### **Planetary gearboxes**

Туре	Cont. torque
R 32	4.5 Nm
R 40	10 Nm

For detailed information, see pages 10 and 11.

# **Feedback options**



### Integral optical encoders

Integrally mounted, metal housed Hewlett Packard encoder modules, 2 or 3 channels TTL output. Optional differential line driver. The RPI option, or rotary pulse indicator, provides a 1 channel TTL output for speed control applications.

For ordering information and available number of lines, see page 11.

#### **Tachogenerators**

Analog feedback devices with iron core or ironless rotor design can be provided upon request.

# **Ordering information**

The listing below provides ordering information for the motors M and integral gearmotors MGM. To order a motor with a high performance gearbox (p 10 and 11) please specify motor and gearbox separately

MGM 9 2 3 2 2 R 24 V 19:1 2 C 500 L A212

MGM 9	Unit type Motor frame size	M = Motor; MGM = Gearmotor 8 = 30 mm; 9 = 40 mm; 14 = 54 mm	
2	Connection and mounting face	1 = leads, 3 holes; 4 = terminals, 4 holes; 2 = leads, 4 holes; 5 = leads, 2 holes; 3 = terminals, 3 holes; 6 = terminals, 2 holes	
3	Magnetisation	Factory assigned. Refer to specification sheets	
2	Motor length	1 = shortest; 7 = longest	
2R	Motor bearing option	1R = 1 ball bearing; $2R = 2$ ball bearings	
24 V	Motor voltage		
19:1	Gear ratio for MGM series Encoder code:		
2 C	Number of channels	1C; 2C; 3C	
500	Number of lines	(see table page 11)	
L	Option	R = rotary pulse indicator; L = line driver	
A212	Factory assigned suffix		